



Redback[®]
N E T W O R K S



Network Processor HW/SW Co-Verification

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Agenda

Redback SmartEdge and PPA – introduction

HW/SW Co-Verification goals

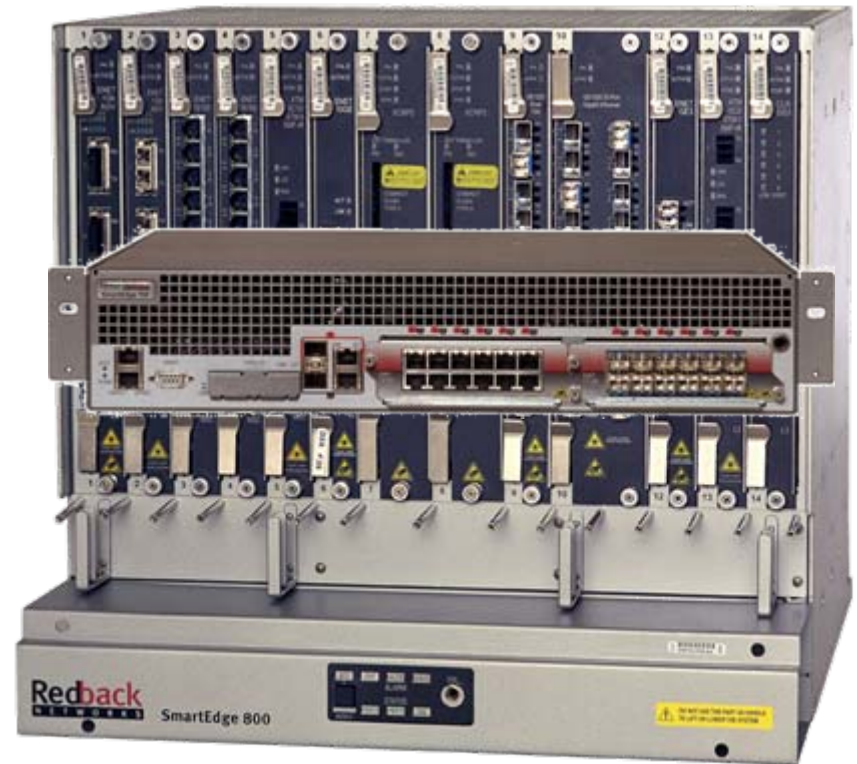
Previous Co-Verification approaches

Cadence Xtreme III

Transaction-Based Acceleration (TBA) approach

Redback Smart Edge Router

- Edge Router
- B-RAS
- Ethernet Aggregation
- Application and Flow aware
- Multiple Line cards



SmartEdge Line Card (1/2)

- **Packet Processing ASICs (PPA)**
 - Multiple execution units (32 EUs) tightly coupled with instruction/data caches
 - Execution units process packets independently
 - Hardware assist offloads critical packet functions such as packet re-ordering, Traffic management
- **Control/data path FPGAs interfaces with PPAs**
- **Proprietary system interfaces to control PPAs and FPGAs**
- **Packet mesh architecture ASIC to connect to back plane**

SmartEdge Line Card (2/2)

- **Two operating systems control PPA and Control/Data path FPGAS**
 - OS1: Responsible for PPA and FPGAs bring-up
 - OS2: Responsible for network admin layer
- **PPAs, FPGAs have local memory and share memory with operating systems**

HW/SW Co-verification goals

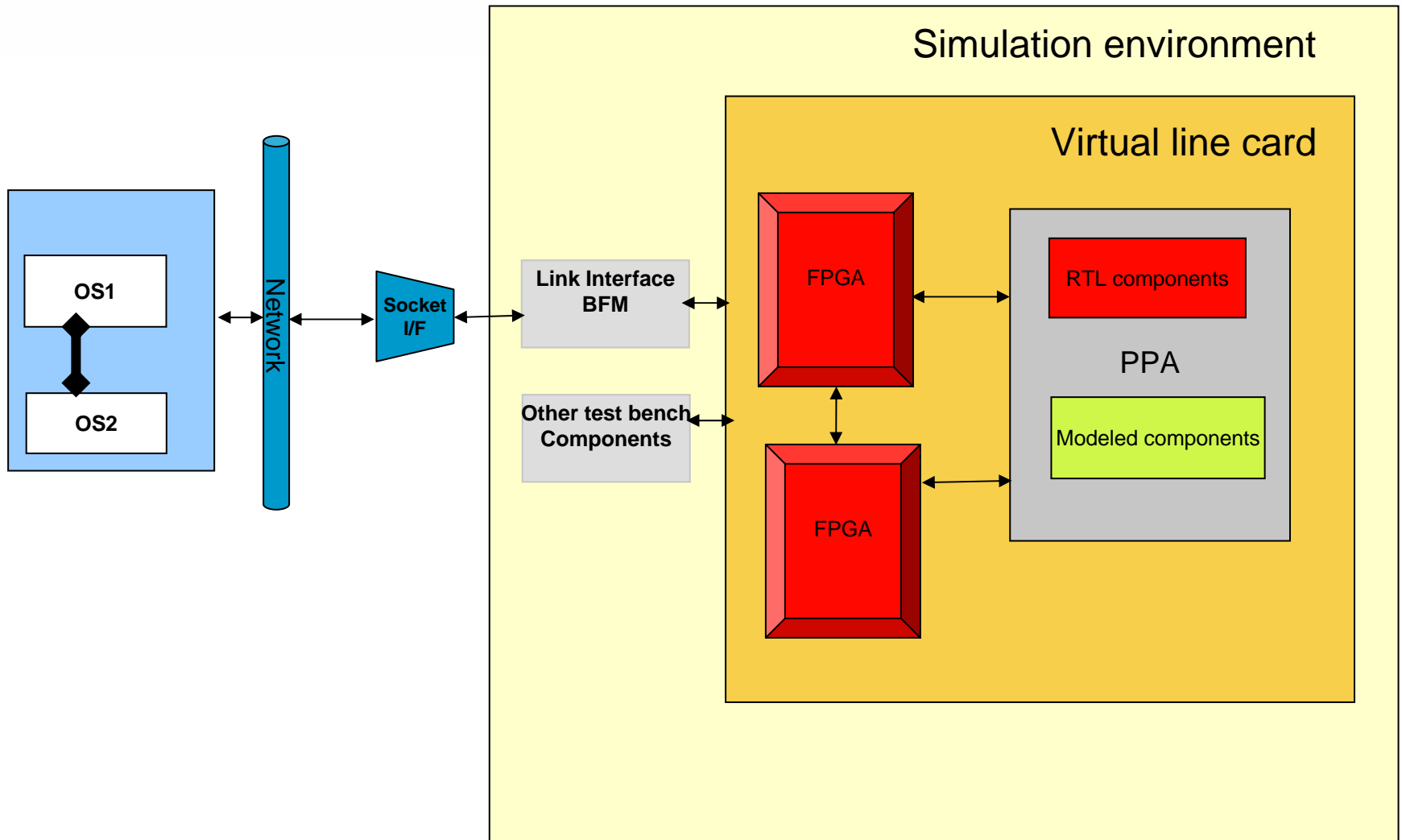
- **Software goals**

- SmartEdge driver development
 - PPA, Control/Data path FPGAs bring-up
- PPA software development can be done in parallel with nextgen chip design
- Performance tuning of software code

- **Hardware goals**

- Running actual software code helps in complete design verification
- Running as a whole system will help identify production issues
- Performance tuning of hardware design
- Accelerate verification regressions

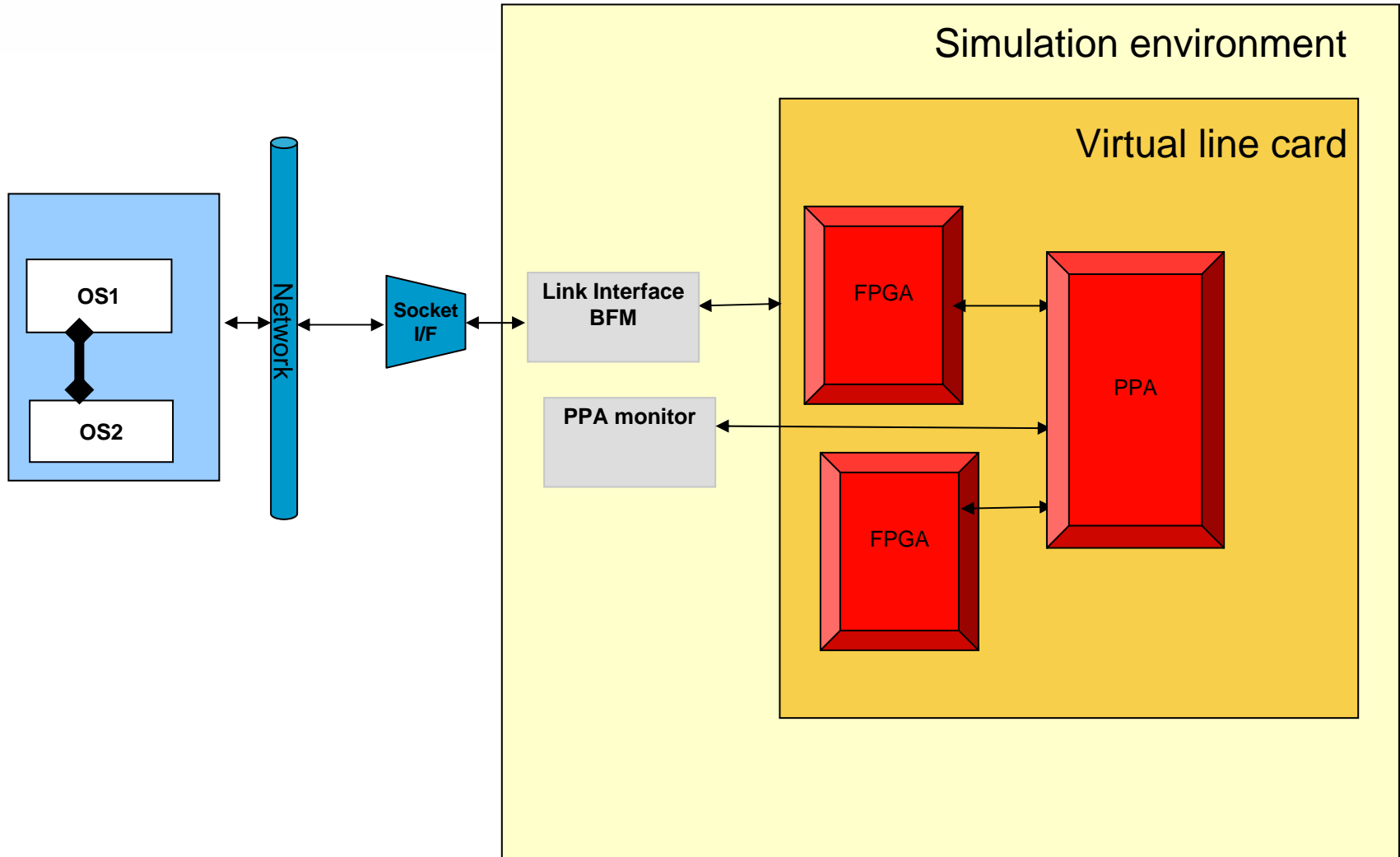
Previous approach (1/2)



Previous approach (2/2)

- Simulation environment consists of some RTL components, modeled components and the test-bench
 - Execution units (EU) were modeled in C language
 - RTL components and the models linked through Programming language interface (PLIs)
 - Test-bench modules mainly present to initialize the PPA
- **Driver by-passes some of the bring-up tasks to speed-up simulation**
 - Example: Back-door writes to initialize memory
- **Since full RTL is not used because of simulation performance, only certain portion of the bring-up driver code is developed.**

Modified approach (1/2)



Modified approach (2/2)

- **Modified approach replaces the modeled components with RTL**
 - This simulates code running on real system
- **PPA bring-up takes 6-7 hours**
- **\$save feature of the software simulator is used to save initialized state of the RTL**
 - Saved 6-7 hours of simulation time
 - Not all test bench state can be saved
 - Special hook-ups needed to save PLI states
- **60 million nano seconds worth of simulation time (without dumping) takes 2 ½ days for a test-case**
 - Test case changes means the simulation needs to run from the restored state and wait for another 2 days!
 - Test bench changes means whole simulation needs to be started from time 0.
- **Simulation becomes slower when dump is enabled**

Cadence Xtreme III (1/3)

- **Comprised of two tightly coupled components that provide single simulation solution**
 - Xcite SIMulator (XSIM): The software component
 - IEEE-complaint event driven HDL software simulator
 - ReConfigurable Computing (RCC) engine: The hardware component
 - Implemented as an array of FPGA that accelerates the RTL and gate-level evaluation
 - Tight coupling to XSIM for simulation and debugging
 - Automatic FPGA partitioning and routing of designs through a single compilation process
- **RTL and gate-level netlist are mapped into RCC**
- **Behavioral-level elements and testbenches are supported by the host workstation**

Cadence Xtreme III (2/3)

- **Extended memory ideal for designs containing or interfacing with large memory designs**
- **Four simulation modes**
 - Traditional software simulation mode
 - RCC acceleration mode
 - Targetless emulation mode
 - In-circuit verification mode
- **Supports Standard Co-Emulation Modeling Interface (SCE-MI 1.1) and Cadence Transaction Based Acceleration (TBA) extensions**
 - Abstract testbench components running on the host machine communicate with the DUT running on the Xtreme III using SCEMI transactors

Cadence Xtreme III (3/3)

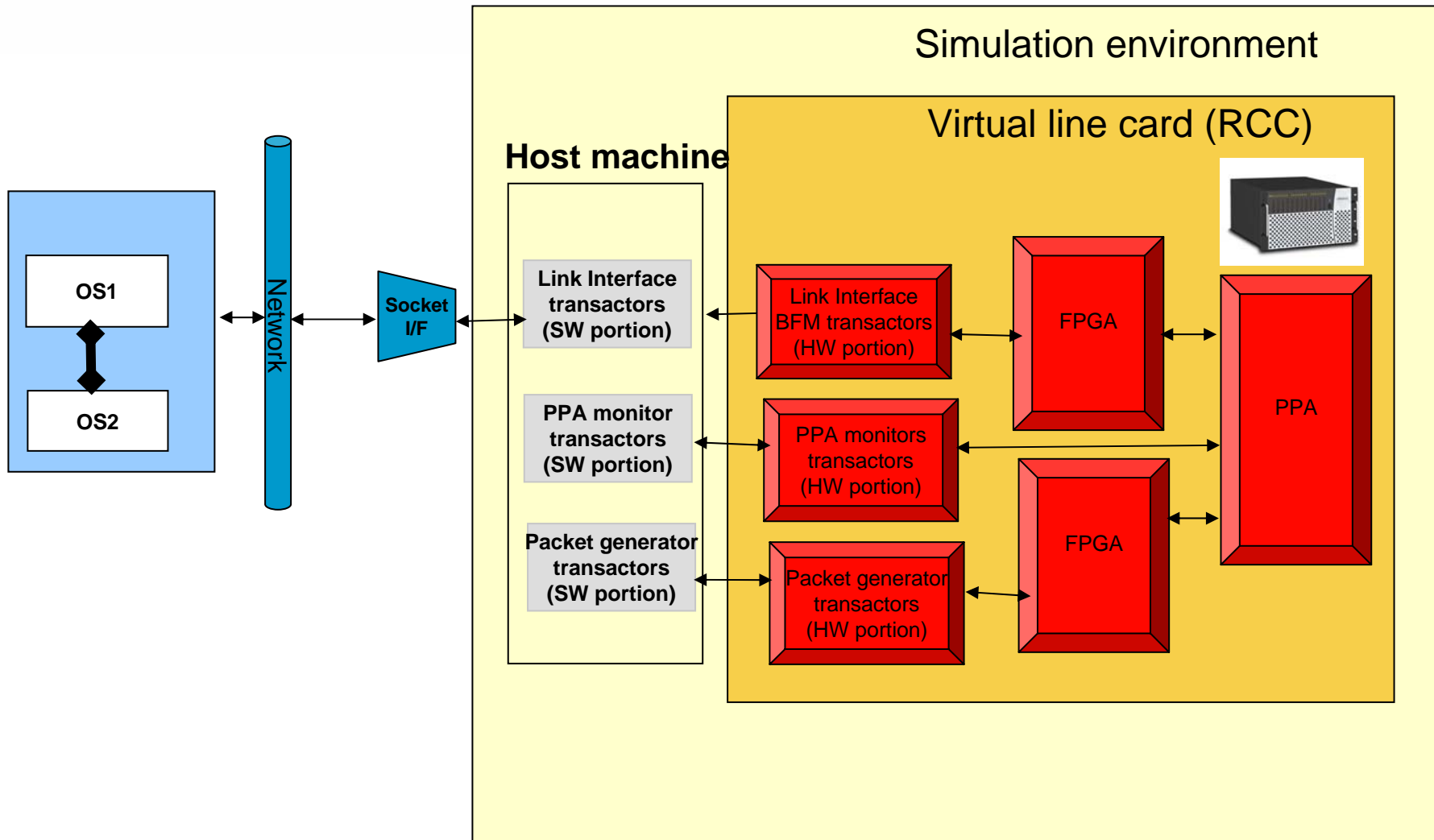
- **VCD on demand (VoD)**

- Waveform can be generated either during simulation or afterwards
- Recording mechanism minimally impacts simulation performance and produce very small record files, so a simulation can always run with “record” on

- **Hot-swapping:**

- Dynamically change between software simulation and acceleration mode

Transaction-based acceleration approach (1/2)



TBA approach (2/2)

- DUT is mapped to RCC and run on the Xtreme III
- Transactors are used
 - BFM is modeled using verilog constructs that can be synthesized and run on Xtreme III
 - BFM interacts with DUT interface based on the signal-level protocol definition of the bus interface
 - Software portion of the transactors (Proxy models) are run on the host machine
 - BFM and the software proxy models communicate among each other by exchanging messages through SCE-MI interface
- Cadence TBA SCEMI extensions are used to aid further simulation speed-up
 - Variable length multi-word messages are supported
 - Multiple message batching improves runtime performance

TBA approach: Summary/Conclusion

- PPA and Control/Data path bring-up now takes 10 minutes
- PPA self-initialization takes an hour to complete

	Old approach	TBA approach
PPA and Control/Data path bring-up	6-7 hours	10 minutes
PPA self initialization	Never ran completely	1 hour
PPA software test cases (60m ns)	2.5 days	2 hours
Debug	Slows down runtime considerably	100% visibility is available without performance penalty

TBA approach: Future plans

- **We are using this approach for next generation PPA software development**
- **We have plans to incorporate this approach for next generation chip development**
- **Plans to identify performance bottle-necks**



CONNECT: IDEAS

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